Lecture 3: Approximation Algorithms for Packing Problems in Two Dimensions

Helmut Alt, Freie Universität Berlin at 10th Winter School on Computational Geometry Amirkabir University of Technology, Tehran

2 March 2018

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Consider a strip S of fixed height.

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Consider a strip S of fixed height.

Given: A set \mathcal{O} of axes-parallel rectangles.

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Determine: Packing of \mathcal{O} into S of minimum length.

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 - 1. Sort the rectangles of ${\mathcal O}$ non-increasing width.

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 - 1. Sort the rectangles of ${\mathcal O}$ non-increasing width.
 - 2. Pack the rectangles at the left end of the strip from bottom to top.

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many heuristics that yield constant factor approximations simplest ones:

- ► Next-Fit.
 - 1. Sort the rectangles of ${\mathcal O}$ non-increasing width.
 - 2. Pack the rectangles at the left end of the strip from bottom to top.
 - 3. If no more space on top, start a new level right of the previous one and continue.

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both are approximation algorithms with factors 3 and 2.7 for FF and NF, respectively !

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- 2. Keep track of the rectangle areas obtained in step 1 and return the rectangle and packing achieving the minimum of these areas.

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- ► The best approximation algorithm for strip packing known achieves a factor of 5/3 + ε for any ε > 0 (Harren et al. 2014)
- For any ε > 0 there is an 5/3 + ε-approximation algorithm for finding the smallest a.p. rectangle for packing a given set of rectangles under translation.

(Alt, de Berg, Knauer, JOCG 2017)

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set P of arbitrary convex polygons

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- set P of arbitrary convex polygons
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- approximating the minimum area convex container for P under translations

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- 3. cut the small boxes for the different height-classes into rectangles of equal width $2w_{max}$, stack all these rectangles, and return the resulting rectangle

important observations about the optimal packing area:

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area used in step 2:

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- 1. $OPT \ge$ the total area of the polygons
- 2. $OPT \geq h_{max} \cdot w_{max}$

area used in step 2:



important observations about the optimal packing area:

- 1. $OPT \ge$ the total area of the polygons
- 2. $OPT \geq h_{max} \cdot w_{max}$

area used in step 2:





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- 1. group the polygons of P into height classes: $[h_{max}, h_{max}/2), [h_{max}/2, h_{max}/4)...$
- within each class i, i = 0, 1, ...: sort the objects by descending slopes (∈ [0, π]) of their spines and place them as far left as possible into an axis-parallel rectangle of height h_{max}/2ⁱ

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3. cut the small boxes for the different height-classes into rectangles of equal width $2w_{max}$ and stack all these rectangles, and return the resulting rectangle

- 1. group the polygons of *P* into height classes: $[h_{max}, h_{max} \cdot \alpha), [h_{max} \cdot \alpha, h_{max} \cdot \alpha^2)...$
- within each class i, i = 0, 1, ...: sort the objects by descending slopes (∈ [0, π]) of their spines and place them as far left as possible into an axis-parallel rectangle of height h_{max} · αⁱ

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3. cut the small boxes for the different height-classes into rectangles of equal width cw_{max} , and stack all these rectangles, and return the resulting rectangle

- 1. group the polygons of *P* into height classes: $[h_{max}, h_{max} \cdot \alpha), [h_{max} \cdot \alpha, h_{max} \cdot \alpha^2)...$
- 2. within each class i, i = 0, 1, ...sort the objects by descending slopes ($\in [0, \pi]$) of their spines and place them as far left as possible into an axis-parallel rectangle of height $h_{max} \cdot \alpha^i$
- 3. cut the small boxes for the different height-classes into rectangles of equal width cw_{max} , and stack all these rectangles, and return the resulting rectangle

gives an approximation factor of $f(\alpha, c) = (1 + \frac{1}{c}) \cdot \frac{2 + c\alpha}{\alpha - \alpha^2}$

this is optimal for $\alpha = 0.407..., c = 2.214...$, namely 17.449...

















Algorithm for arbitrary convex containers

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1. Find an orientation $\phi \in S^1$ which minimizes $h_{max}(\phi)w_{max}(\phi)$.

Algorithm for arbitrary convex containers

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2. Use the previous algorithm with respect to orientation ϕ .

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1. An approximation to the minimum area axis parallel rectangle can be found in $O(n \log n)$ time.

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- 1. An approximation to the minimum area axis parallel rectangle can be found in $O(n \log n)$ time.
- 2. An approximation to the minimum area convex container can be found in $O(n \log n)$ time.

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- 1. An approximation to the minimum area axis parallel rectangle can be found in $O(n \log n)$ time. Approximation factor: 18
- 2. An approximation to the minimum area convex container can be found in $O(n \log n)$ time.

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- 1. An approximation to the minimum area axis parallel rectangle can be found in $O(n \log n)$ time. Approximation factor: 18
- 2. An approximation to the minimum area convex container can be found in $O(n \log n)$ time. Approximation factor: $16 + 8\sqrt{3} = 29.86.$